

1 On the use of double quantile regression 2 and visual assessment to estimate 3 performance constraints

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5 We recently published evidence that male Adelaide's warblers' vocal performance improves
6 over the course of the dawn chorus (Vazquez-Cardona et al., 2023). In that study, vocal
7 performance was measured as the distance from an estimated performance limit in acoustic
8 space (Logue, Sheppard, Walton, Brinkman, & Medina, 2020). We used mixed quantile
9 regression (QR) to estimate performance limits (Logue & Bonnell, 2023; Wilson, Bitton, Podos,
10 & Mennill, 2014). Visual inspection of scatterplots showed the QR lines approximated the slopes
11 of the constrained edges of the distributions. We took this as evidence that the lines accurately
12 represent how the two variables trade off at the limits of performance. A recent paper by
13 Cardoso (2024) argues that there were two important flaws with our approach.

14 Cardoso's (2024) first critique is that our performance metrics ("deviation scores") incorrectly
15 emphasize one of the two acoustic variables from which they are derived. He writes that
16 deviation scores derived from QR lines tend to correlate strongly with one of the two acoustic
17 variables that trade-off at the limit of performance. He gives the example of our deviation score
18 *recovery time*, which is based on the trade-off between the duration of a note, and the duration
19 of the subsequent silent gap. *Recovery time* correlated more strongly with gap duration ($r =$
20 0.94), than it did with note duration ($r = 0.24$), because the slope of the QR line was low ($\beta =$
21 0.17). According to Cardoso (2019, 2024), the assignment of variables to axes is largely
22 arbitrary, and if the axes were switched, the deviation score would emphasize the other variable
23 (note duration, in this case). Following this logic, *recovery time*'s emphasis on gap duration is
24 arbitrary and does not reflect the species' biology. Cardoso's preferred solution is to perform
25 double quantile regression (DQR). To conduct a DQR, one first conducts a QR of x on y , then
26 reverses the axes and runs a QR of y on x . If the edge of interest has a negative slope we can
27 use the same τ for both QRs. If, however, it has a positive slope, we should use $\tau_{\text{inverted}} = 1 -$
28 τ_{original} so that QR can estimate the constrained edge in both orientations (Cardoso, Abreu, Archer,
29 Crottini, & Mota, 2020). The deviation scores from these two regression lines can then be
30 averaged to generate deviation scores that are not biased by the assignment of variables to
31 axes.

32 Cardoso (2024) is also concerned that uneven sampling is responsible, in part or in whole, for
33 the appearance of performance constraints in our data plots. As evidence, he provides several
34 plots of unconstrained, unevenly sampled simulated data (Fig. 2 in Cardoso 2024). These plots,
35 he argues, spuriously indicate the existence of a constraint. The acoustic data from Vazquez-
36 Cardona et al. (2023) are unevenly sampled (i.e., data are denser in some regions of the x-axis
37 than others), so the appearance of constraints on our scatterplots may also be misleading. If
38 that is true, then visual assessment would produce biased estimates of performance constraints
39 and the deviation scores derived from them. Cardoso (2024) argues that visual assessment is

40 therefore not appropriate for estimating the slopes of performance constraints. Instead, he
41 writes, we should use DQR to estimate constraints.

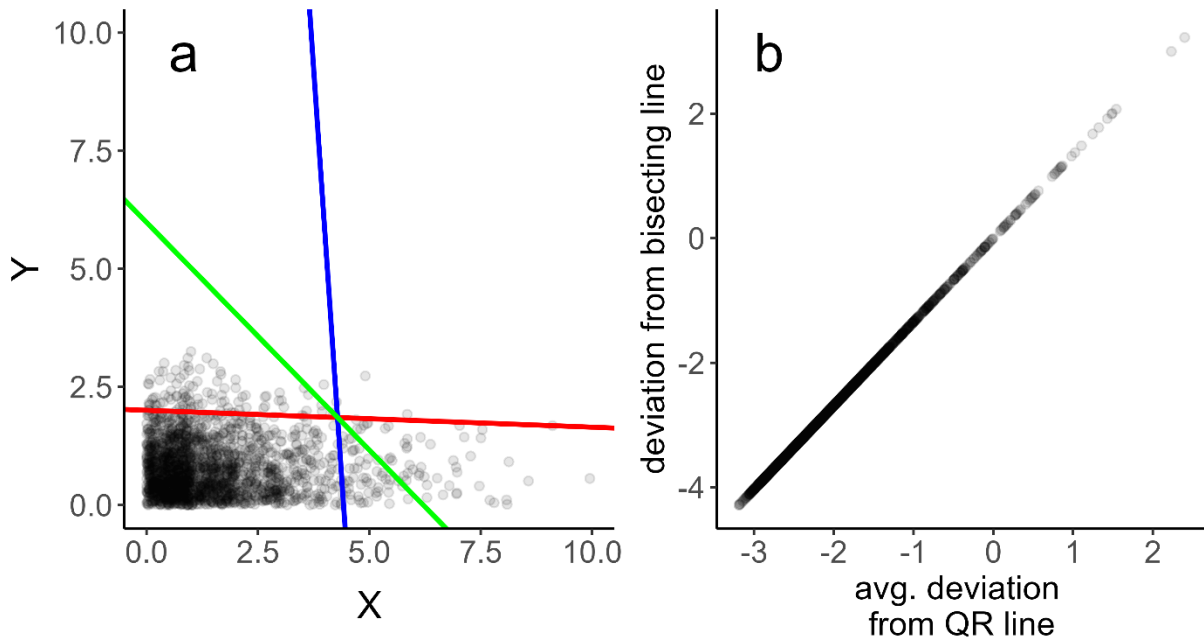
42 What are we trying to do with quantile regression?

43 Before we address Cardoso's critique, it is worthwhile to explain what QR does and why we
44 used it. Quantile regression produces a straight line that best estimates some quantile y
45 (defined by y) over the range of x . Students of performance constraints, however, do not want to
46 estimate a particular quantile, *per se*. Rather, we want to estimate the slope of one edge of a
47 two-dimensional distribution of data for which there is *a priori* evidence of constraint (Logue &
48 Bonnell 2023). Cardoso (2024) seems to agree with this goal, as evidenced by his Fig. 1, in
49 which two datapoints (\times and \square) that are equidistant from the edge of the distribution are said to
50 have "similar performance." The edge of the distribution, however, is not necessarily well-
51 described by QR (Logue et al. 2020, Vazquez-Cardona et al. 2023).

52 Consider two distributions that have the same, positively sloping, upper boundary. If the lower
53 boundary of Distribution 1 is parallel to the upper boundary, but the lower boundary of
54 Distribution 2 slopes in the opposite direction, QR analysis of the upper boundary will produce
55 different slope estimates, even though the upper boundaries of the two distributions (i.e., the
56 slopes we want to estimate) are identical. Although QR is an imperfect tool to estimate the slope
57 of an edge, it can often do a passable job when applied to a large dataset and combined with
58 visual inspection.

59 Our methods follow Vazquez-Cardona et al. (2023) except where stated. All analyses were
60 conducted in R 4.3.2 (Team, 2013) running in the R Studio environment (RStudio Team, 2020).
61 We used *lqmm* (Geraci, 2014) for mixed quantile regression, *quantreg* (Koenker et al., 2018) for
62 quantile regression without random terms, *patchwork* (Pedersen, 2019) for composite graphs,
63 and *tidyverse* (Wickham et al., 2019) for data manipulation and visualization.

64 One way to test Cardoso's (2019) assertion that DQR produces a less-biased estimate than QR
65 would be to compare the edge of the distribution to the slope estimates produced by QR and
66 DQR. The version of double quantile regression described in Cardoso (2019), however, does
67 not generate a single consensus slope estimate. Rather, it generates two slope estimates based
68 on QR, calculates deviation scores from each one, and averages them. We hypothesized that a
69 line that bisects the angles created by the two QR lines would describe a consensus DQR line
70 whose deviation scores would be equivalent to the average scores from the constituent QRs. To
71 test this hypothesis, we compared the average deviation scores of the two DQR lines (the
72 output of a DQR), to the deviation scores from one of the two lines that bisects the DQR lines.
73 We found that the deviation scores from the bisecting line scaled linearly with the average of the
74 deviation scores from the two QR lines (Fig. 1). Thus, the bisecting line characterizes how DQR
75 sees the edge of a data distribution and we can use its slope to help determine whether DQR is
76 appropriate for a given dataset. Typically, researchers will not know the true slope of the edge,
77 so they will not have a "gold standard" against which to compare the estimated slopes (but see
78 analysis of simulated data below). Visual inspection of a scatterplot, however, can tell us
79 whether the estimate approximates the edge.

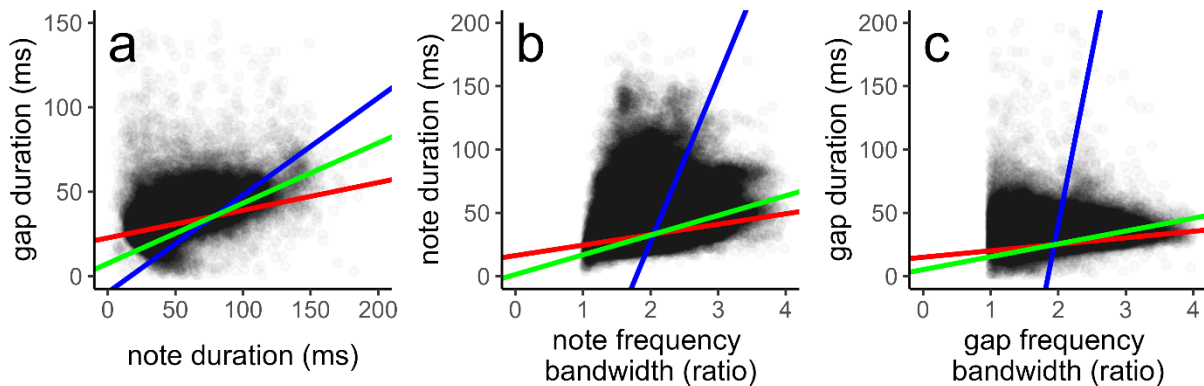


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81 **Fig. 1.** (a) A scatterplot of simulated, unevenly sampled, unconstrained data from Cardoso
 82 (2024) showing the original (red) and inverted (blue) quantile regression lines, and their bisector
 83 (green). (b) Plot comparing the average of deviations from the two QR lines to the deviations
 84 from the bisecting line.

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86 We conducted DQR on the acoustic data from Vazquez-Cardona et al. (2023) to see whether
 87 the bisecting lines estimated the slope of the distributions' constrained edges more accurately
 88 than the lines from our original QR analysis. Based on our visual comparison of the slope of the
 89 bisecting line and the slope of the constrained edge of the distribution, DQR estimates were as
 90 good as or better than estimates based on QR (Fig. 2). For two of the comparisons, however,
 91 the QR lines derived from the inverted data (blue lines in Figs. 2b and 2c) appeared to have
 92 radically different slopes than the edges of their respective distributions. We will return to this
 93 finding later.



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95 **Figure 2.** Scatterplots comparing pairs of acoustic variables from the notes of male Adelaide's
 96 warbler songs. In each case, the lower boundary of the distribution is hypothesized to be
 97 constrained. Lines show the results of quantile regression ($\alpha = 0.05$) in the original orientation

98 (red) and the inverted orientation (blue), as well as their bisecting line (green). Axes have been
99 cropped to aid visualization, so some extreme outliers are missing. The bisecting lines do not
100 appear to bisect the angles on these graphs because the axes have different scales.
101

102 Is it problematic when QR lines emphasize one variable?

103 We now address Cardoso's (2024) first argument, which is that single QR arbitrarily emphasizes
104 one of the two variables that trade off at the limit of performance. Visual assessment indicates
105 that the constrained edges of our data distributions form a shallow angle with the x-axis. We
106 therefore expect the deviation scores to be influenced by (and thus correlate with) the y-variable
107 more than the x-variable. This makes sense biologically. Consider the performance metric
108 *unvoiced FM* which is a deviation score derived from the trade-off between the frequency
109 bandwidth and duration of the silent gaps between notes. The data indicate that, at the limit of
110 performance, an increase of 1 SD in frequency bandwidth requires an increase in gap duration
111 of < 1 SD. We see no biological reason to expect that constraints should impose one-to-one
112 trade-offs in general.

113 Cardoso (2024, 2019) writes that the assignment of variables to the x- and y-axes is largely
114 arbitrary. For some distributions, however, only one orientation is amenable to QR. For QR to
115 accurately estimate the slope of the constrained edge of a distribution, the constrained edge
116 must comprise the entire top or bottom of the distribution. For some distributions, this only
117 occurs in one of the two possible orientations. Our *recovery time* data is amenable to lower
118 boundary (low) QR in the original orientation and upper boundary (high) QR in the inverted
119 orientation (Fig. 3a, 3a'). Both orientations permit QR to approximate the slope of the
120 constrained edge, and the bisecting line fits the edge better than either of the single QR lines
121 (Fig. 2a). However, the same cannot be said of our other two comparisons. Our *unvoiced FM*
122 data permits lower boundary QR when gap frequency BW is assigned to the x-axis and gap
123 duration is assigned to the y-axis (Fig. 3c). When we inverted the axes, however, the
124 constrained edge comprised neither the top nor the bottom of the distribution (Fig. 3c'). QR on
125 the inverted data produces a line that does not approximate the slope of the constrained edge.
126 The same is true for the *voiced FM* data. Cardoso's (2024) suggestion to transform the data
127 (e.g., by multiplying by -1) does not eliminate this problem.

128 We can generalize from these examples to predict whether inversion will expose the
129 constrained edge to QR. If the facet of the distribution opposite the constrained edge has the
130 opposite slope as the constrained edge (e.g., the constrained edge is positively sloped and the
131 opposite edge is negatively sloped), a QR on the inverted distribution will "see" both the
132 constrained edge and the opposite edge, and so return a line that does not accurately
133 characterize the slope of the constrained edge (Figs. 2,3).

134 We tested the performance of QR and DQR on distributions in which the edge of interest and
135 the opposite edge have opposite slopes. We simulated two-dimensional data with opposite-
136 sloping constraints on the lower (intercept = 0, slope = 0.25) and upper (intercept = 8, slope = -
137 0.5) facets of the distribution. We then conducted QR and DQR on the lower boundary ($\alpha = 0.05$).
138 The QR analysis returned an estimated slope of 0.15, which was 0.1 less than the true slope.
139 The DQR analysis, however, estimated the slope as -0.2, which was 0.45 less than the true
140 slope. When tasked with estimating the slope of the lower boundary in a simulated dataset with

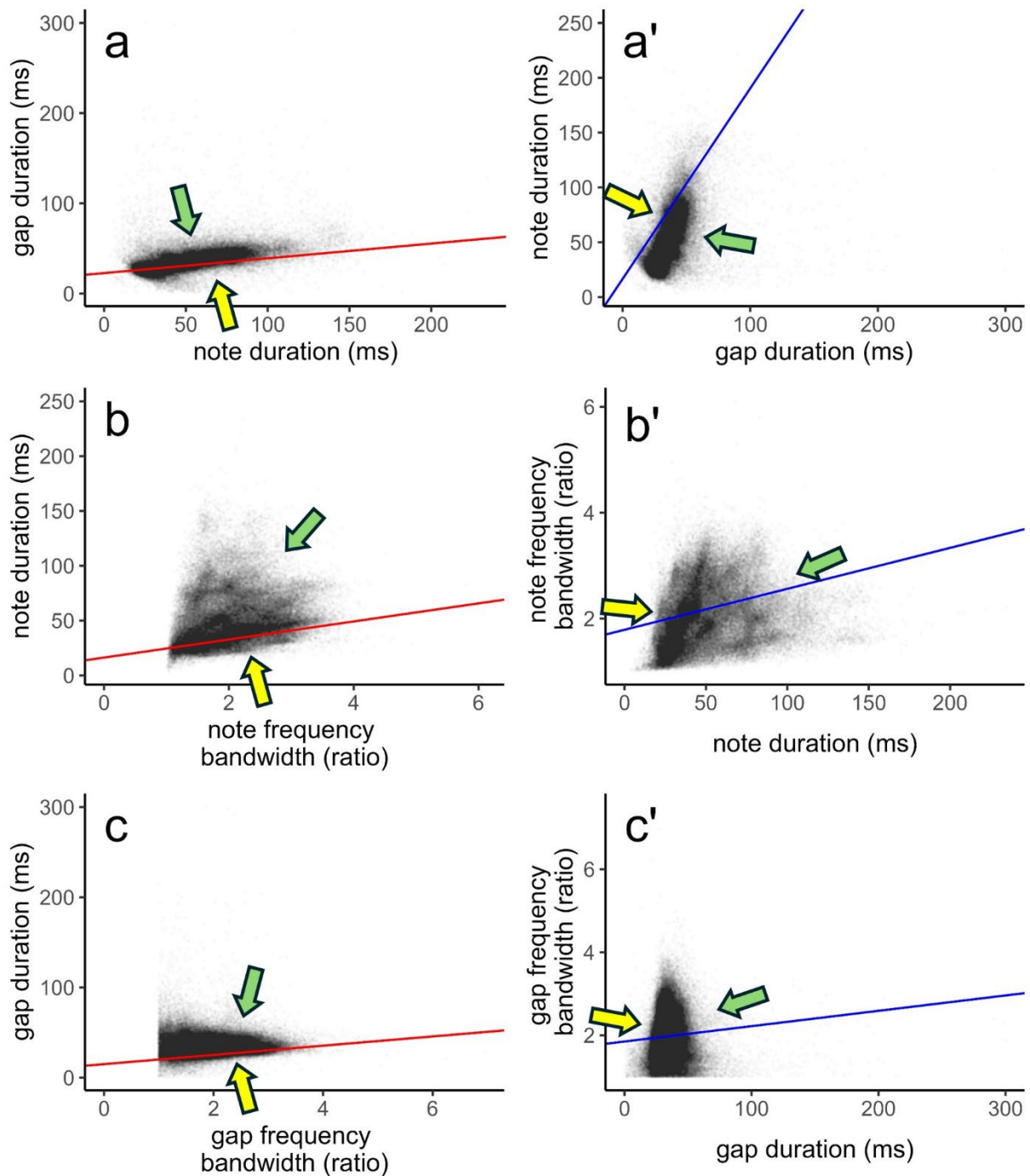
141 opposite sloped boundaries on the upper and lower facets neither estimate was very accurate,
142 but QR was much more accurate than DQR.

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144 Uneven sampling and the illusion of constraint

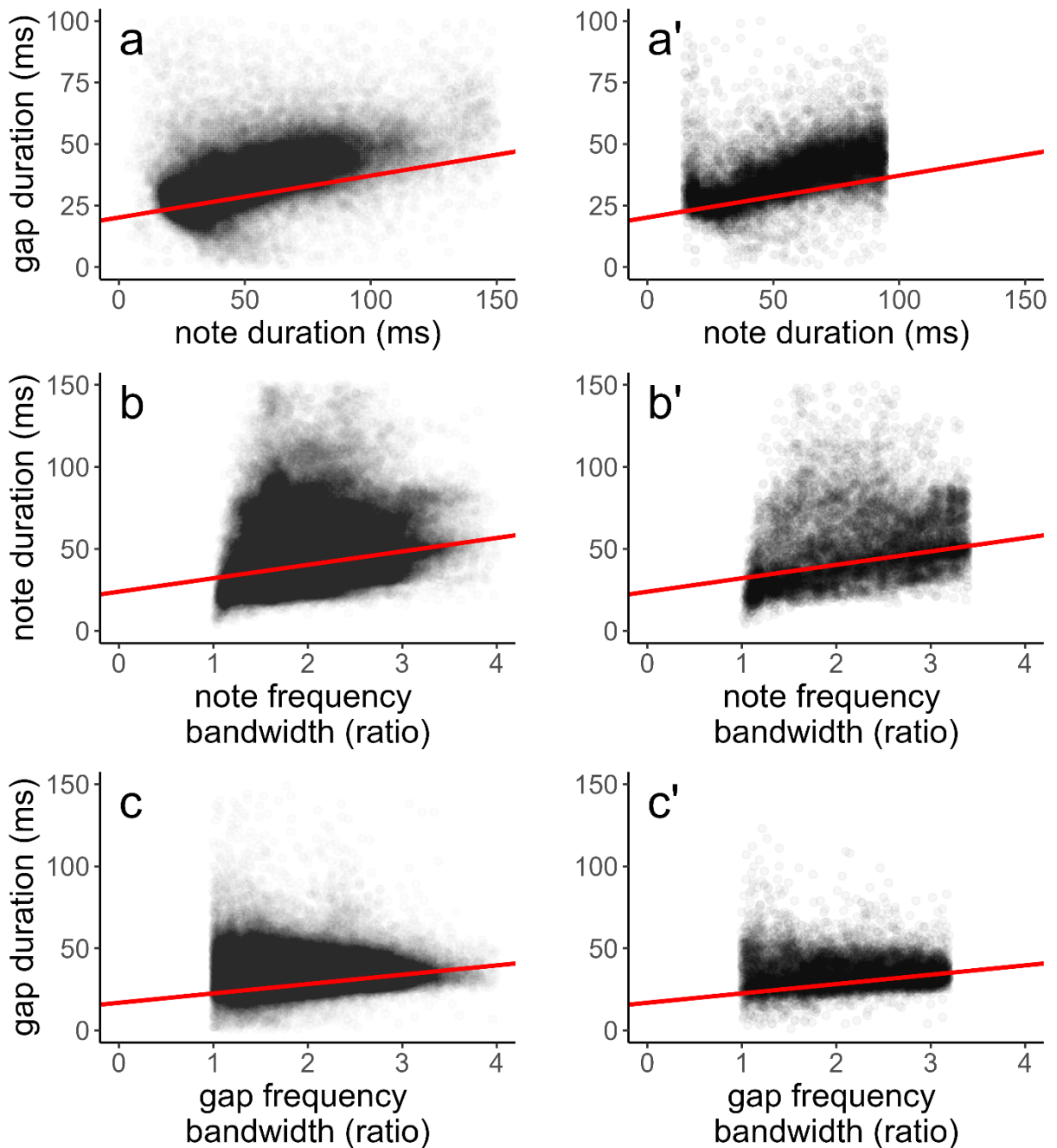
145 Up to this point, we have assumed that visual inspection of the scatterplot is an accurate way to
146 estimate the slope of the constrained edge. Cardoso (2024), however, argues that visual
147 inspection is a poor way to estimate the slope of a distribution's edge because uneven sampling
148 alone can produce the illusion of constraint. In support of this argument, Cardoso presents
149 unevenly sampled distributions of simulated data that are unconstrained but nevertheless
150 appear to have sloped edges (e.g., Fig. 2a in Cardoso 2024). He points out that the data in
151 Vazquez-Cardona (2023) are also unevenly sampled, so the appearance of constraint may be
152 an artifact of uneven sampling. We tested this hypothesis.

153 If the sloping lower boundary of a distribution is an artifact of uneven sampling, it should
154 disappear when sampling is even. Rarefaction ensures even sampling by drawing a fixed
155 number of samples from each of several equal-sized bins. We rarefied our data, leaving 1000
156 samples in each bin (*recovery time*: bin size = 5 ms; *voiced FM* and *unvoiced FM*: bin size =
157 0.2). Extreme values of x did not include enough samples in each bin, so we truncated the data.
158 We then compared plots of the rarefied data to plots of the whole dataset (Fig. 4). Rarefaction
159 had little effect on the visibility or slope of the lower boundaries of the scatterplots.



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Figure 3. Scatterplots of note-level acoustic data from male Adelaide's warblers. (a-c) Scatterplots in the orientation they were analyzed for previous studies (Logue et al. 2020, Vazquez-Cardona et al. 2023). (a'-c') Scatterplots with the axes reversed relative to previous studies. Lines are from quantile regression with $\alpha = 0.05$ (red lines) or $\alpha = 0.95$ (blue lines). Arrows indicate the constrained edge of the distribution (yellow) and the opposite edge (green). Points are smaller and lighter than in Figure 2.



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 170 **Figure 4.** Scatterplots of note-level acoustic variables from male Adelaide's warblers. Plots a-c
 171 are based on the complete dataset, whereas plots a' – c' are based on rarefied data. Points are
 172 semi-transparent to show density (a-c: alpha = 0.01; a' – c': alpha = 0.03). Red lines are the
 173 quantile regression lines used to estimate the edge of the distribution in Vazquez-Cardona et al.
 174 (2023).

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 177 We noticed an important difference between the scatterplots of our bird song data and the plots
 178 of simulated data in Cardoso (2024). The bird song plots show distributions with sharply defined
 179 lower edges, whereas the simulated distributions do not show edges at all, but rather smooth

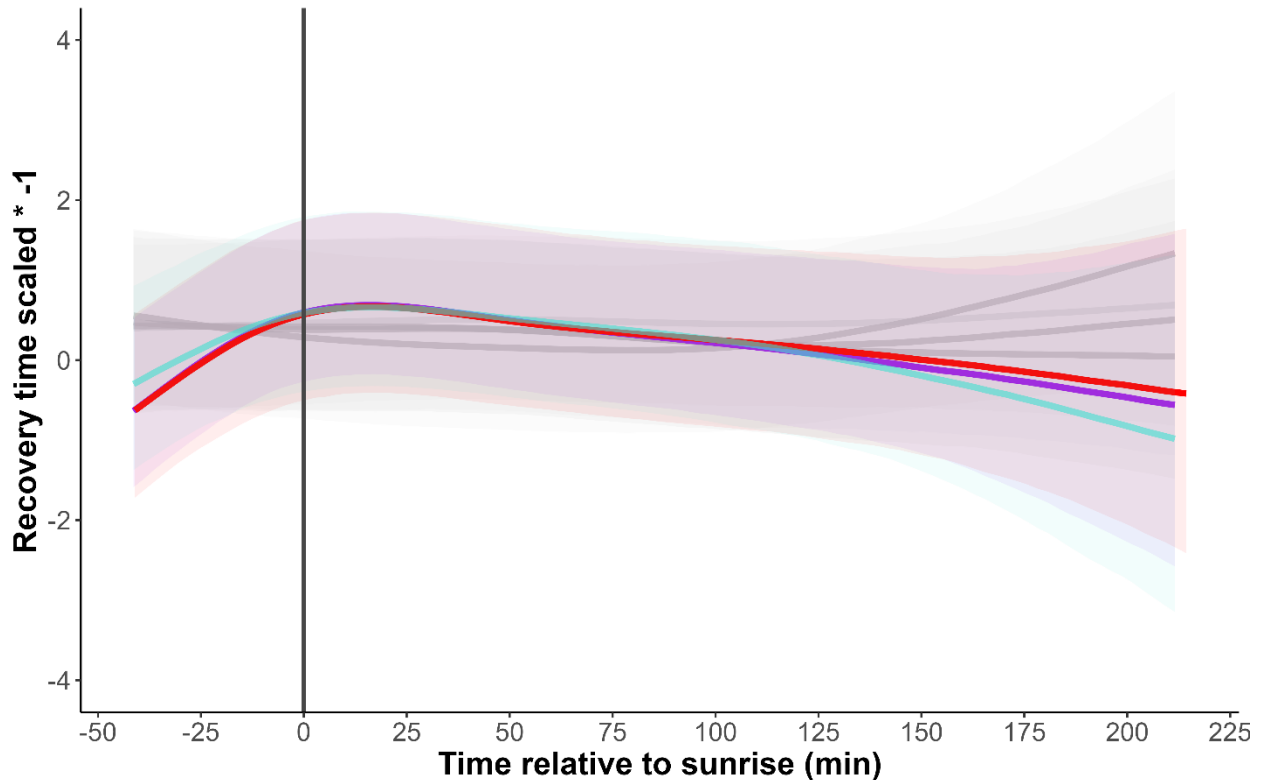
180 density gradients (compare our Fig. 4a-4c with Fig. 2 from Cardoso 2024). Our group has
181 previously shown that constrained edges are characterized by steep clines, not diffuse gradients
182 (Logue et al. 2020, Logue and Bonnell 2023). We conclude that motor constraints generate
183 sloped edges on trade-off plots, but uneven sampling generates sloping gradients. This
184 difference can be detected by visual inspection of scatterplots (Logue & Bonnell 2023).

185 We evaluated QR and DQR's performance on unconstrained data (Fig. 1a). When we applied
186 single QR to the unconstrained, unevenly sampled, simulated data that is the basis of Cardoso's
187 (2024) Fig. 2a, we found little evidence of a sloped edge, regardless of the orientation of the
188 data ($\text{slope}_{\text{original}} = -0.04$, $\text{slope}_{\text{inverted}} = -0.07$; red and blue lines in Fig. 1a). In contrast, the
189 bisecting line that shows how DQR characterizes the edge of the distribution is strongly sloped
190 ($\text{slope}_{\text{bisecting}} = -0.96$; green line in Fig. 1a). In this case, single QR correctly estimates that there
191 is not a sloped edge, but DQR treats an unbounded distribution as if it were bounded. When
192 using DQR, one should be careful not to identify boundaries where none exist. Another potential
193 shortcoming of DQR is that, unlike single QR, it does not provide any measure of confidence
194 (e.g., confidence intervals or a p-value) that the edge of the slope is not flat.

195 Finally, we tested Cardoso's (2024) hypotheses that the effect of warming up on *recovery time*
196 reported in Vazquez-Cardona et al. (2023) was exaggerated due to uneven sampling, and that
197 substituting DQR for single QR would weaken or eliminate the pattern. We also tested the
198 uneven sampling hypothesis by running the same Bayesian mixed model from Vazquez-
199 Cardona et al. (2023) using *recovery time* deviation scores based on the QR line from the
200 rarefied data. If uneven sampling exaggerated the warm-up effect by biasing the estimate of the
201 trade-off between gap duration and note duration, we should see a reduced effect when
202 deviation scores are measured from a QR line derived from rarefied data. This was not the
203 case. The slope of the QR line based on the rarefied dataset was identical to the slope based
204 on the full dataset ($\beta = 0.17$). When we ran the deviation scores through the Bayesian mixed
205 model from Vazquez-Cardona et al. (2023), we found a nearly identical pattern to the original:
206 Performance was lowest first thing in the morning, improved rapidly during the dawn chorus,
207 and decreased gradually thereafter (Fig. 5).

208 We tested whether DQR would eliminate or weaken the observed pattern by using DQR to
209 calculate *recovery time* and running the results through our model. We still saw the same basic
210 pattern: performance was low when birds began singing, improved rapidly during the dawn
211 chorus, and gradually diminished thereafter. We quantified the "warm-up effect" as the
212 estimated improvement in performance from 2460 seconds before sunrise to the time of
213 sunrise. The estimated warm-up effect when we used QR to measure recovery time (1.2 SD)
214 was slightly greater than the one based on DQR (0.9 SD). The decrease in performance
215 between sunrise and 12,000 seconds after sunrise was greater for the estimates based on DQR
216 (1.4 SD) than for those based on QR (0.9 SD). Thus, the performance estimates based on DQR
217 indicated a slightly weaker warm-up effect, and a slightly stronger cool-down effect. Notably,
218 however, both effects are well within the credible intervals estimated by the QR-based model.
219 We ran four iterations of the DQR model with shuffled data. None of these indicated a warm-up
220 effect (average warmup = -0.1 SD; Fig. 5), indicating that the estimated warm-up effect in the
221 DQR-based model exceeds null expectations.

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224 **Figure 5.** A plot showing the estimated conditional effect of time on the performance metric
 225 mean *recovery time*. *Recovery time* was measured with quantile regression applied to the full
 226 dataset (red line, as in Vazquez-Cardona et al. 2023), quantile regression applied to rarefied
 227 data (purple line), and double quantile regression applied to the full dataset (turquoise line).
 228 Gray lines use the same data as the turquoise line, but data were shuffled prior to analysis. Pale
 229 bands represent 95% credible intervals.

230 Summary and Discussion

231 We conducted a series of analyses to address Cardoso’s (2024) critique of Vazquez-Cardona et
 232 al. (2023). We found mixed evidence for Cardoso’s (2024) assertions that the deviation scores
 233 in Vazquez-Cardona et al. (2023) incorrectly emphasize one of the two acoustic variables from
 234 which they are derived, and that DQR should be used to reduce this bias. While we reject his
 235 argument that asymmetric correlations between deviation scores and the variables that
 236 comprise them are evidence of bias, our analyses indicate that DQR can improve the fit of the
 237 regression line to the edge for some distributions (Fig. 2).

238 We did not find support for Cardoso’s (2023) hypothesis that uneven sampling is responsible for
 239 the appearance of performance constraints in our data. Rarefaction had little effect on the
 240 constrained edge of the data distribution, demonstrating that uneven sampling is not responsible
 241 for the appearance of constraint (Fig. 4). Further, basing the QR line on rarefied data had almost
 242 no effect on the performance metric *recovery time*’s change over time (Fig. 5). Cardoso (2024,
 243 p. 3) hypothesized that due to uneven sampling, “the real effect [of warm-up on recovery time] is
 244 likely weaker or maybe non-existent,” compared to what was indicated in Vazquez-Cardona et
 245 al. (2023). We found that DQR does provide a better estimate of the distribution’s edge in the
 246 *recovery time* comparison, but the improvement does not appear to be attributable to uneven

247 sampling. While the warm-up effect was slightly weaker when we used DQR, the overall pattern
248 of change over time remained the same, confirming our original conclusion that birds warm up
249 their voices during the dawn chorus.

250 While uneven sampling can bias the slope of a QR line, it does not mimic the effects of
251 constraint. Uneven sampling in the absence of constraint produces a smooth density gradient,
252 whereas constraint produces a sharper cline in density (Logue & Bonnell 2023). Given a
253 sufficiently large sample size, visual assessment can reveal this difference.

254 We recommend using the bisecting line to characterize the fit of a DQR analysis. Previously, we
255 attempted to characterize how DQR sees the constrained edge by averaging the slopes and
256 intercepts of the QR lines from the original orientation and the inverted orientation (electronic
257 supplemental material for Vazquez-Cardona et al. 2023). Cardoso (2024) was skeptical that the
258 average line characterized DQR, and indeed it does not. One of the two bisecting lines,
259 however, does. Bisecting lines that parallel the constrained edge of the distribution indicate
260 good fit.

261 When and how, then, should students of performance constraints use DQR? We found that
262 applying QR to inverted distributions can produce slope estimates that do not approximate the
263 constrained edge when the constrained edge slopes in the opposite direction of the opposite
264 edge. Even in these cases, however, DQR can sometimes improve slope estimates (Fig. 2). Our
265 analysis of our own synthesized data, and that of Cardoso, showed that DQR can also produce
266 spurious slope estimates that are inferior to those from QR. We therefore advise caution with
267 DQR when the constrained edge of a distribution slopes away from the opposite edge (Fig. 3).

268 DQR appears to be a useful approach for estimating the slope of a constrained edge when the
269 opposite facet of the distribution does not slope away from the constrained edge (Cardoso
270 2019, 2024). However, DQR can return strong slopes when there are no constraints and it does
271 not give an estimate of uncertainty, so it should be used in combination with other methods, like
272 visual inspection of scatterplots, rarefaction, single QR, and analysis of skew (Logue & Bonnell
273 2023). All these methods are more effective when samples are large. Looking to the future, the
274 field would benefit from the development of tools that characterize the edge of a distribution
275 directly, rather than methods like QR and DQR that estimate quantiles.

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